

- 3.22.** A. The system is linear, so we can find the response to each term in the input expression and add the responses together.

For input  $2 \cos\left(\frac{\pi}{2}n\right)$ , we can evaluate  $H(z)$  at  $z = e^{j\frac{\pi}{2}}$ . The steady-state response is then  $\left|H\left(e^{j\frac{\pi}{2}}\right)\right| 2 \cos\left(\frac{\pi}{2}n + \angle H\left(e^{j\frac{\pi}{2}}\right)\right)$ .

For input  $u[n]$ , the steady-state response is equal to the DC gain; that is,  $H(e^{j0})$ .

- B. Given  $H(z) = \frac{1-4z^2}{1+0.5z^{-1}}$ , we have

$$H\left(e^{j\frac{\pi}{2}}\right) = \frac{1-4e^{-j\pi}}{1+0.5e^{-j\frac{\pi}{2}}} = \frac{5}{1-j0.5} = 4.47e^{j0.464}.$$

Then  $y_1[n] = 8.94 \cos\left(\frac{\pi}{2}n + 0.464\right)$ .

Next,  $H(e^{j0}) = \frac{1-4}{1+0.5} = -2.00$ , so that  $y_2[n] = -2.00 \times 1 = -2.00$ .

As  $n$  gets large the response becomes

$$y[n] = y_1[n] + y_2[n] = -2.00 + 8.94 \cos\left(\frac{\pi}{2}n + 0.464\right).$$

3.32. (a)

$$\begin{aligned} X(z) &= \frac{1}{(1 + \frac{1}{2}z^{-1})^2(1 - 2z^{-1})(1 - 3z^{-1})} \quad \frac{1}{2} < |z| < 2 \\ &= \frac{\frac{1}{35}}{(1 + \frac{1}{2}z^{-1})^2} + \frac{\frac{88}{1225}}{(1 + \frac{1}{2}z^{-1})} - \frac{\frac{1568}{1225}}{(1 - 2z^{-1})} + \frac{\frac{2700}{1225}}{(1 - 3z^{-1})} \end{aligned}$$

Therefore,

$$x[n] = \frac{1}{35}(n+1) \left(\frac{-1}{2}\right)^{n+1} u[n+1] + \frac{58}{(35)^2} \left(\frac{-1}{2}\right)^n u[n] + \frac{1568}{(35)^2} (2)^n u[-n-1] - \frac{2700}{(35)^2} (3)^n u[-n-1]$$

(b)

$$X(z) = e^{z^{-1}} = 1 + z^{-1} + \frac{z^{-2}}{2!} + \frac{z^{-3}}{3!} + \frac{z^{-4}}{4!} + \dots$$

Therefore,  $x[n] = \frac{1}{n!} u[n]$ .

(c)

$$X(z) = \frac{z^3 - 2z}{z - 2} = z^2 + 2z + \frac{2}{1 - 2z^{-1}} \quad |z| < 2$$

Therefore,

$$x[n] = \delta[n+2] + 2\delta[n+1] - 2(2)^n u[-n-1]$$

- 3.46.** 1. Given  $x[n] = -\frac{1}{3}\left(\frac{1}{2}\right)^n u[n] - \frac{4}{3}(2)^n u[-n-1]$ , we have

$$\begin{aligned} X(z) &= \frac{-\frac{1}{3}}{1 - \frac{1}{2}z^{-1}} + \frac{\frac{4}{3}}{1 - 2z^{-1}} \\ &= \frac{1}{\left(1 - \frac{1}{2}z^{-1}\right)\left(1 - 2z^{-1}\right)}, \quad \frac{1}{2} < |z| < 2. \end{aligned}$$

2. The expression

$$Y(z) = \frac{1 - z^{-2}}{\left(1 - \frac{1}{2}z^{-1}\right)\left(1 - 2z^{-1}\right)}$$

can converge for a)  $|z| < \frac{1}{2}$ , b)  $\frac{1}{2} < |z| < 2$ , or c)  $2 < |z|$ . However,  $Y(z) = H(z)X(z)$ , where  $H(z)$  is the system function of the given LTI system, and the ROC of  $Y(z)$  must contain the intersection of the ROC of  $H(z)$  with the ROC of  $X(z)$ . Since  $X(z)$  has ROC  $\frac{1}{2} < |z| < 2$ , only choice b) is possible.

3. The system function  $H(z)$  is given by

$$H(z) = \frac{Y(z)}{X(z)} = 1 - z^{-2}, \quad 0 < |z|.$$

The only choice for difference equation is

$$y[n] = x[n] - x[n-2].$$

4. The only choice for impulse response is

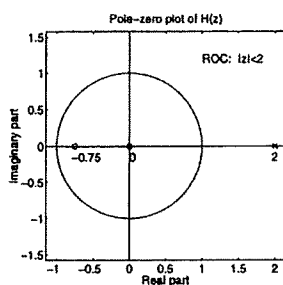
$$h[n] = \delta[n] - \delta[n-2].$$

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- 3.48. (a) Since  $y[n]$  is stable, its ROC contains the unit-circle. Hence,  $Y(z)$  converges for  $\frac{1}{2} < |z| < 2$ .  
 (b) Since the ROC is a ring on the  $z$ -plane,  $y[n]$  is a two-sided sequence.  
 (c)  $x[n]$  is stable, so its ROC contains the unit-circle. Also, it has a zero at  $\infty$  so the ROC includes  $\infty$ . ROC:  $|z| > \frac{3}{4}$ .  
 (d) Since the ROC of  $x[n]$  includes  $\infty$ ,  $X(z)$  contains no positive powers of  $z$ , and so  $x[n] = 0$  for  $n < 0$ . Therefore  $x[n]$  is causal.  
 (e)

$$\begin{aligned} x[0] &= X(z)|_{z=\infty} \\ &= \frac{A(1 - \frac{1}{4}z^{-1})}{(1 + \frac{3}{4}z^{-1})(1 - \frac{1}{2}z^{-1})}|_{z=\infty} \\ &= 0 \end{aligned}$$

- (f)  $H(z)$  has zeros at  $-0.75$  and  $0$ , and poles at  $2$  and  $\infty$ . Its ROC is  $|z| < 2$ .



- (g) Since the ROC of  $h[n]$  includes  $0$ ,  $H(z)$  contains no negative powers of  $z$ , which implies that  $h[n] = 0$  for  $n > 0$ . Therefore  $h[n]$  is anti-causal.